

Draw-wire Sensors – Measuring Wheels



Encoders with a prefixed draw-wire sensor (0.25 to 40 m long) are the best choice for direct length measurements. Thanks to the excellent repeatability rating of 0.05 mm, they solve position control tasks with the utmost precision in applications which, up to now, could only be handled by complex equipment.

Whether used for positioning of pumps in tanks, for alignment of elevating platforms or orientation of cranes: Just select a draw-wire sensor of the right size and with the appropriate output configuration for your system.

Technical data	Measuring range	Type code		
Analog current output,	250 mm	DW250-70-7E-H1441		
420 mA,	500 mm	DW500-70-7E-H1441		
2-wire, $U_{R} = 1230 \text{ VDC},$	1000 mm	DW1000-110-7E-H1441		
M12-male	2000 mm	DW2000-110-7E-H1441		
	3000 mm	DW3000-110-7E-H1441		
	6000 mm	DW6000-155-7E-H1441		
	10000 mm	DW10000-135-7E-H1441		
	15000 mm	DW15000-135-7E-H1441		
	20000 mm	DW20000-135-7E-H1441		
	30000 mm	DW30000-135-7E-H1441		
	40000 mm	DW40000-135-7E-H1441		
Potentiometer output,	250 mm	DW250-70-PA-H1441		
1 kΩ,	500 mm	DW500-70-PA-H1441		
$U_B = \text{max. } 30 \text{ VDC},$ M12 male	1000 mm	DW1000-110-PA-H1441		
WITZ Male	2000 mm	DW2000-110-PA-H1441		
	3000 mm	DW3000-110-PA-H1441		
	6000 mm	DW6000-155-PA-H1441		
	10000 mm	DW10000-135-PA-H1441		
	15000 mm	DW15000-135-PA-H1441		
	20000 mm	DW20000-135-PA-H1441		
	30000 mm	DW30000-135-PA-H1441		
	40000 mm	DW40000-135-PA-H1441		



If simple length measurements are required, such as cutting paper or fabrics to length, encoders with a prefixed measuring wheel are the inexpensive but very precisely operating alternative.

Recommended accessory

Spring arm for encoders, adjustable contact pressure, multiple mounting possibilities. Type: RMW-1

Recommended encoder

Incremental, 1 mm resolution, Type: RI-10S10C-2B500-H1181

Material surface	Perimeter/ width	Material	Coating	Operating temperature	Bore for encoder shaft	Type code
Cardboard Wood Fabric		Aluminium	Cross-knurl	-30+80 °C		RMW-5
Cardboard Wood Fabric Paper	-	Aluminium	Hytrel (smooth)	-30+80 °C	-	RMW-6
Cardboard Wood Fabric Paper Wire	0,5 m/ 25 mm	Aluminium	Vulkollan (smooth)	-30+80 °C	- 10 mm	RMW-7
Fabric Metal Coated surface	-	Aluminium	Burled rubber	-30+80 ° C	-	RMW-8
Fabric	-	Aluminium	Hytrel (grooved)	-30+80 °C	-	RMW-9

Accessories

	Accessories	Max. revolution [Ncm]	Max. axial offset [mm]	Max. angular error [°]		Type code
r solid shaft ers	Bellows coupling Ø 19 mm	150	± 0,7	± 1,5	for shaft Ø 0/10	RCS-19-d1-d2 (example RCS-19-10-10)
Accessories for encode	PAGUFLEX® cou- pling	3	15	15	Bore Ø/mm (fo 10/1010	48 8 127 127 RCS-7

	Accessories	Conditions	For encoders	Reference diameter	Type code
Accessories for hollow shaft encoders	Mounting plate, short	Axial/radial play low dynamics	Ri-12 RS-31 RS-33 RM-35 RM-36	64,5 mm	0 3,65 18 - 9,75 60,3 0,3 - 0,
	Mounting plate, long	Axial/radial play low dynamics	Ri-12 RS-31 RS-33 RM-35 RM-36	80170 mm	0 50 0 35 13.55 78 14.3 7.8 6.3 10.16
	Stator coupling	Axial/radial play high dynamics	Ri-12 RS-31 RS-33 RM-35 RM-36	65 mm	0.5 16 RME-7
	Spring element, long	High axial play	Ri-42	110 mm	0.25 R3.25 7.8 1 5.3 7.8 - 1.0 RME-10
	Insulating inlay for shaft	Reduction/insulation of shaft diameter	Ri-12H15T	d1 = 6 mm	015,5 015 015
	Shaft insert	for electrical isolation	Ri-12H15T	d1 = 12 mm	adiio 45,2 RSA-1, RSA-5
essories draw-wire ensors	Shaft insert	for electrical isolation			0.44 0.47 0.65 0.55 0.55 0.55 0.55

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Overview Encoders









Incremental Encoders

Ri encoder – push-pull with inversion



Incremental encoders use electrical pulses to measure rotation speed or position.

The dual-channel incremental encoders of the Ri series, detect positions bidirectionally as well as the rotation sense of the shaft.

Design	Shaft diameter flange/ mounting	Electrical connection/ operating voltage	Resolution imp.	Type code			
		Solid s	haft				
Compact Ø 37 mm	6 mm without flange	Cable connection $U_{\rm g} = 530 \text{VDC}$	360 500 512 1000 1024	Ri-08S6S-2F360-C 1M Ri-08S6S-2F500-C 1M Ri-08S6S-2F512-C 1M Ri-08S6S-2F1000-C 1M Ri-08S6S-2F1024-C 1M			
0 0		Hollow	shaft				
	8 mm stator coupling	Cable connection U _B = 530 VDC	360	Ri-09H8E-2F360-C 1M			
		Solid s	haft				
	6 mm clamping flange	Cable connection U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-10S6C-2B360-H1181 Ri-10S6C-2B2048-H1181 Ri-10S6C-2B2500-H1181 Ri-10S6C-2B4096-H1181 Ri-10S6C-2B5000-H1181			
Standard Ø 58 mm	10 mm clamping flange	Cable connection U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-10S10C-2B360-H1181 Ri-10S10C-2B360-H1181 Ri-10S10C-2B2500-H1181 Ri-10S10C-2B4096-H1181 Ri-10S10C-2B5000-H1181			
	6 mm synchro flange	Cable connection U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-10S6S-2B360-H1181 Ri-10S6S-2B2048-H1181 Ri-10S6S-2B2500-H1181 Ri-10S6S-2B4096-H1181 Ri-10S6S-2B5000-H1181			
	10 mm synchro flange	Cable connection U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-10S10S-2B3660-H1181 Ri-10S10S-2B2048-H1181 Ri-10S10S-2B2500-H1181 Ri-10S10S-2B4096-H1181 Ri-10S10S-2B5000-H1181			
	Hollow shaft						
	10 mm torque stop	M12 male U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-12H10T-2B360-H1181 Ri-12H10T-2B2048-H1181 Ri-12H10T-2B2500-H1181 Ri-12H10T-2B4096-H1181 Ri-12H10T-2B5000-H1181			
	15 mm torque stop	M12 male U _B = 1030 VDC	360 2048 2500 4096 5000	Ri-12H15T-2B360-H1181 Ri-12H15T-2B2048-H1181 Ri-12H15T-2B2500-H1181 Ri-12H15T-2B4096-H1181 Ri-12H15T-2B5000-H1181			
Large hollow shaft Ø 100 mm	25 mm spring element long	M23 male U _B = 1030 VDC	1024 2048 5000	Ri-42H25S4-2B1024-12M23 Ri-42H25S4-2B5000-12M23 Ri-42H25S4-2B5000-12M23			
	30 mm spring element long	M23 male U _B = 1030 VDC	1024 2048 5000	Ri-42H30S4-2B1024-12M23 Ri-42H30S4-2B2048-12M23 Ri-42H30S4-2B5000-12M23			

Absolute Singleturn Encoders

RS encoder



Absolute singleturn encoders detect any angle within a full revolution of 360°. With absolute encoders, each incremental angle is assigned a code pattern. This allows the position to be detected at any time, even after a power failure, without having to initialize a reference run. Absolute encoders detect angles, positions and inclinations precisely – tasks, that are typically found in robotics, positioning and process technology.

esign	Shaft diameter flange/ mounting	Electrical connection/ operating voltage	Output type/ resolution	Type code			
Solid shaft							
	6 mm synchro flange	Cable connection U _B = 1530 VDC	Analog, U, 010 V, 12 bit	RS-06S6S-8B12B-C 1M			
		Cable connection $U_B = 1030 \text{ VDC}$	Analog, I, 420 mA, 12 bit	RS-06S6S-7A12B-C 1M			
Compact Ø 36 mm		Cable connection $U_B = 530 \text{ VDC}$	SSI, binary 9 bit	RS-54S6S-5B9B-C 1M			
om 36		Hollow sha	aft				
Ŭά	6 mm stator coupling	Cable connection $U_B = 1530 \text{ VDC}$	Analog, U, 010 V, 12 bit	RS-07H6E-8B12B-C 1M			
		Cable connection $U_B = 1030 \text{ VDC}$	Analog, I, 420 mA, 12 bit	RS-07H6E-7A12B-C1M			
		Cable connection $U_B = 530 \text{ VDC}$	SSI, binary 9 bit	RS-55H6E-5B9B-C 1M			
		Solid shaf	t				
	6 mm clamping flange	M12 male U _B = 1030 VDC	SSI Gray 13 bit	RS-24S6C-3C13B-H1481			
		M12 male U _B = 1030 VDC	PROFIBUS 16 bit	RS-25S6C-9A16B-R3M12			
	10 mm clamping flange	M12 male U _B = 1030 VDC	SSI, Gray 13 bit	RS-24S10C-3C13B-H1481			
		M12 male U _B = 1030 VDC	PROFIBUS 16 bit	RS-25S10C-9A16B-R3M12			
dard mm	6 mm synchro flange	M12 male U _B = 1030 VDC	SSI, Gray 13 bit	RS-24S6S-3C13B-H1481			
Standard Ø 58 mm		M12 male U _B = 1030 VDC	PROFIBUS 16 bit	RS-25S6S-9A16B-R3M12			
	10 mm synchro flange	M12 male U _B = 1030 VDC	SSI, Gray 13 bit	RS-24S10S-3C13B-H1481			
		M12 male U _B = 1030 VDC	PROFIBUS 16 bit	RS-25S10S-9A16B-R3M12			
	Hollow shaft						
	12 mm stator coupling	M12 male U _B = 1030 VDC	SSI, Gray 13 bit	RS-31H12E-3C13B-H1181			
		M12 male U _B = 1030 VDC	PROFIBUS 16 bit	RS-33B12E-9A16B-R3M12			

Absolute Multiturn Encoders

RM encoder



Absolute multiturn encoders detect any angle within a full revolution of 360° and also the number of revolutions. With absolute encoders, each incremental angle is assigned a code pattern. This allows the position to be detected at any time, even after a power failure, without having to initialize a reference run. Absolute encoders detect angles, positions and inclinations precisely – tasks, that are typically found in robotics, positioning and process technology.

esign	Shaft diameter flange/ mounting	Electrical connection/ operating voltage	Output type/ resolution	Type code			
		Solid shaf	t				
36 mm	8 mm synchro flange	Cable connection UB = 1030 VDC	SSI, Gray 12/12 bit	RM-46S8S-3C24B-CT 1M			
36		Hollow sha	aft				
i Ø	10 mm stator coupling	Cable connection UB = 1030 VDC	SSI, Gray 12/12 bit	RM-50H10E-3C24B-CT 1M			
		Solid shaf	t				
	6 mm clamping flange	M12 male U _B = 1030 VDC	SSI, Gray 13/12 bit	RM-28S6C-3C25B-H1181			
		M12 male U _B = 1030 VDC	PROFIBUS 16/12 bit	RM-29S6C-9A28B-R3M12			
	10 mm clamping flange	M12 male U _B = 1030 VDC	SSI, Gray 13/12 bit	RM-28S10C-3C25B-H1181			
mm 85 Ø		M12 male U _B = 1030 VDC	PROFIBUS 16/12 bit	RM-29S10C-9A28B-R3M12			
	6 mm synchro flange	M12 male $U_B = 1030 \text{ VDC}$	SSI, Gray 13/12 bit	RM-28S6S-3C25B-H1181			
		M12 male U _B = 1030 VDC	PROFIBUS 16/12 bit	RM-29S6S-9A28B-R3M12			
	10 mm synchro flange	M12 male U _B = 1030 VDC	SSI, Gray 13/12 bit	RM-28S10S-3C25B-H1181			
		M12 male $U_B = 1030 \text{ VDC}$	PROFIBUS 16/12 bit	RM-29S10S-9A28B-R3M12			
	Hollow shaft						
	12 mm stator coupling	M12 male U _B = 1030 VDC	SSI, Gray 13/12 bit	RM-35H12E-3C25B-H1181			
		M12 male U _B = 1030 VDC	PROFIBUS 16/12 bit	RM-36B12E-9A28B-R3M12			



High protection class

A protection rating of as high as IP69K can be achieved, even under the most adverse application conditions, thanks to the excellently protected shaft seal. The devices always work safely and reliably, even in the roughest environments



High accuracy

High-quality components and an innovative quality management provide highly precise measured signals for excellent linearity and repeatability. Even the most demanding applications are economically and technically viable with TURCK encoders.



Rugged designs

Balanced stainless steel clamp rings and highly rugged bearing-shaft constructions improve the stability and reliability of the devices, making them resistant to extremely heavy mechanical impacts. Thanks to the new design, the encoders are made for heavy duty applications and highest revolution speeds.



High interference immunity

Frequency converters, large motors, ferritic metals or permanent magnets are no problem at all: The optically operating encoders are insensitive to magnetic fields of all kinds and feature excellent EMC properties.



Shock and vibration proof

The extremely rugged bearing assembly guarantees high stability of the shaft in case of vibration and other mechanical loads. Blocked bearings, enough spacing between the bearings and extra strong outer bearings prevent interferences and machine downtimes emerging from intense load. These are strains which mechanically complex applications are often exposed to.



Extensive Accessories

A wide range of accessories is available to ensure easy installation and safe operation.